

# New Algorithms for Multivalued Component Trees

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## Motivation

The component tree (CT) [3] can model grey-level images for various image processing / analysis purposes (filtering, segmentation, registration, retrieval...). Its generalized version, the multivalued component tree (MCT) [1] can model images with hierarchically organized values. We provide new tools to handle MCTs:

- a new algorithm for the construction of MCTs;
- two strategies for building hierarchical orders on values, required to further build MCTs.

## Multivalued Component Tree

Let  $\Theta = (\Omega, \prec)$  be a non-directed graph. Let  $\mathcal{C}[X]$  be the set of the connected components of  $X \subseteq \Omega$ . Let  $\mathbb{V}$  be a finite set and  $\leq$  a hierarchical order on  $\mathbb{V}$ , i.e. an order (1) which admits a minimum (resp. a maximum) and (2) such that for any  $v \in \mathbb{V}$ , the subset of the elements lower (resp. greater) than  $v$  is totally ordered by  $\leq$ .

Let us consider an image  $\mathcal{F} : \Omega \rightarrow \mathbb{V}$ . The threshold set of  $\mathcal{F}$  at value  $v \in \mathbb{V}$  is defined by  $\Lambda_v(\mathcal{F}) = \{\mathbf{x} \in \Omega \mid v \leq \mathcal{F}(\mathbf{x})\}$ . We define the set of nodes of the MCT as

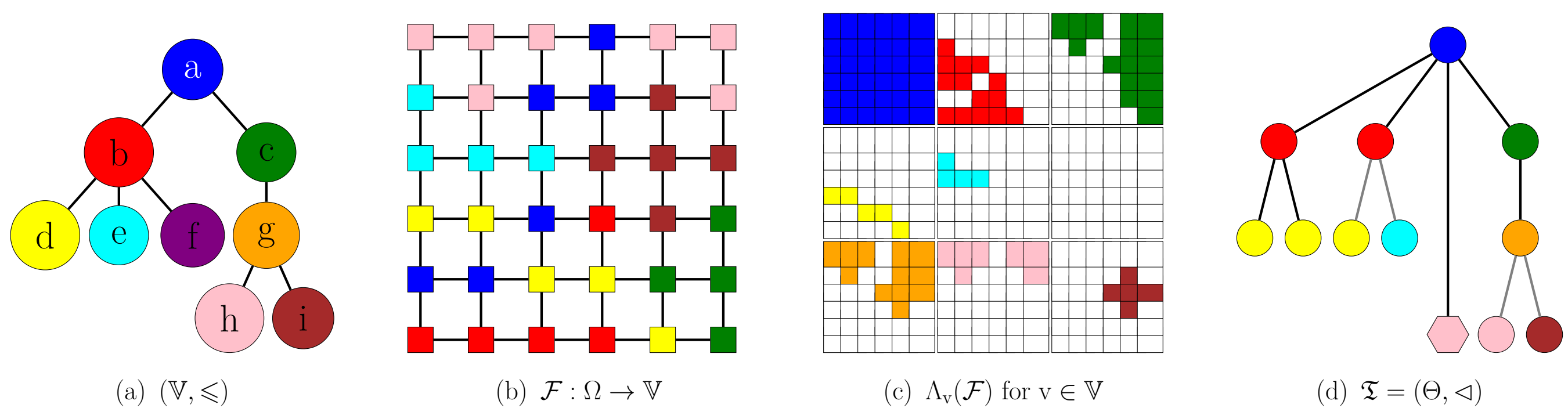
$$\Theta = \bigcup_{v \in \mathbb{V}} \mathcal{C}[\Lambda_v(\mathcal{F})] \quad (1)$$

with  $\mathbb{I}(X) = \{v \in \mathbb{V} \mid X \in \mathcal{C}[\Lambda_v(\mathcal{F})]\}$ ,  $\omega(X) = \bigvee^{\leq} \mathbb{I}(X)$  and  $\tau(X) = |\mathbb{I}(X)|$  for any node  $X \in \Theta$ .

The inclusion relation  $\subseteq$  is a hierarchical order on  $\Theta$ . Let  $\triangleleft$  be the reflexive-transitive reduction of  $\subseteq$ . The Hasse diagram  $\mathfrak{T} = (\Theta, \triangleleft)$  of  $(\Theta, \subseteq)$  is the multivalued component tree of the image  $\mathcal{F}$ . For any node  $X \in \Theta$ , we set  $\rho(X) = X \setminus \bigcup_{Y \triangleleft X} Y = \{\mathbf{x} \in \Omega \mid \mathcal{F}(\mathbf{x}) = \omega(X)\}$ .

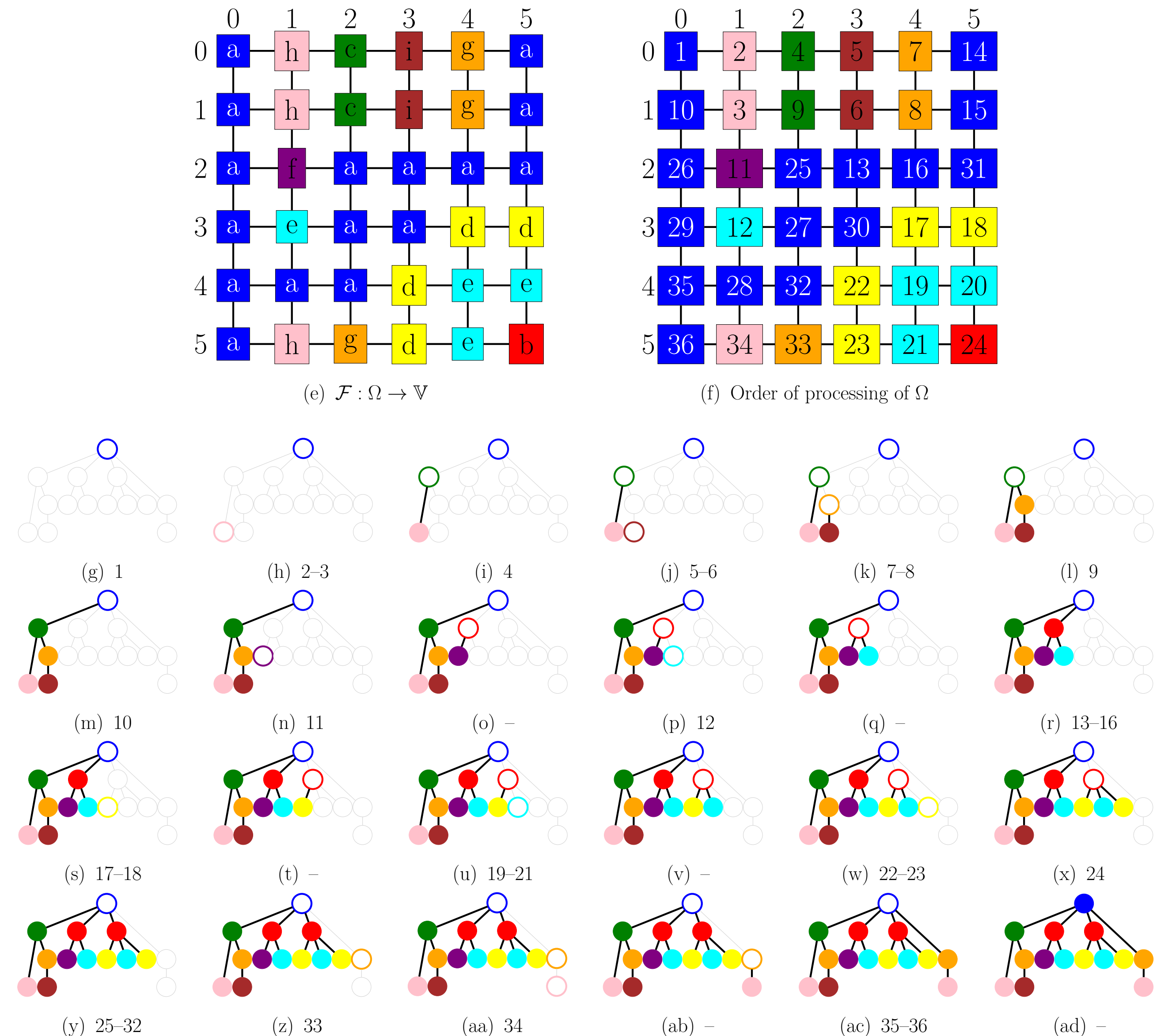
The MCT  $\mathfrak{T}$  is an image model of the image  $\mathcal{F}$ :

$$\forall \mathbf{x} \in \Omega, \mathcal{F}(\mathbf{x}) = \bigvee_{X \in \Theta} \mathbf{1}_{(X, \omega(X))}(\mathbf{x}) \quad (2)$$



## Running the Construction Algorithm

Construction of the MCT of an image  $\mathcal{F} : \Omega \rightarrow \mathbb{V}$ . At a current stage: a plain coloured node is fully built; a contour-coloured node is under construction; a non-coloured node has not been considered yet; a black edge is built; a light gray edge is not built.



## Building the Multivalued Component Tree

This construction algorithm derives from the CT construction of [3].

- **nodes**: stores the nodes of the multivalued component tree.
- **points**: stores the processed points of the image.
- **status**: stores the status of each point of the image.
- **nb\_nodes** and **index**: store the number of nodes already fully built and the index of the node currently built at each value of  $\mathbb{V}$ .
- **progress**: indicates if there exists a node at value  $v$ , currently under construction or to be built, which is an ancestor of the node at value  $u$  currently being defined.

Algorithm 1: Build the multivalued component tree

Input:  $(\Omega, \prec), (\mathbb{V}, \leq), \mathcal{F} : \Omega \rightarrow \mathbb{V}$

Output:  $\mathfrak{T} = (\Theta, \triangleleft)$

Build **nodes**, **points**, **status**, **nb\_nodes**, **index**, **progress**

$v_{\min} := \bigwedge^{\leq} \mathbb{V}$

Choose  $\mathbf{x}_{\min} \in \Omega$  such that  $\mathcal{F}(\mathbf{x}_{\min}) = v_{\min}$

**points**[ $v_{\min}$ ].add( $\mathbf{x}_{\min}$ )

**progress**[ $v_{\min}$ ] := true

Flood( $v_{\min}$ )

Function Flood

Input:  $u \in \mathbb{V}$ : current level

Output:  $w \in \mathbb{V}$ : value of the parent node of the root of the built (partial) MCT at value  $u$

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while !(points[ $u$ ].empty()) do
     $\mathbf{x} := \mathbf{points}[u].\text{remove}()$ 
    if  $\mathbf{index}[u] > \mathbf{nb\_nodes}[u]$  then
         $\mathbf{nb\_nodes}[u] := \mathbf{index}[u]$ 
         $X := \text{create\_node}()$  // new node in  $\Theta$ 
         $\mathbf{nodes}[u].\text{insert}(X)$ 
    if  $\mathcal{F}(\mathbf{x}) \neq u$  then
         $w := \mathcal{F}(\mathbf{x})$ 
         $\mathbf{points}[w].\text{add}(\mathbf{x})$ 
         $\mathbf{progress}[w] := \text{true}$ 
        while  $u < w$  do  $w := \text{Flood}(w)$ 
    else
         $\mathbf{status}[\mathbf{x}] := \mathbf{index}[u]$ 
         $\mathbf{nodes}[u][\mathbf{index}[u]].\text{add\_to\_proper\_part}(\mathbf{x})$ 
        foreach  $\mathbf{y} \sim \mathbf{x}$  do
             $w := \mathcal{F}(\mathbf{y})$ 
            if  $\mathbf{status}[\mathbf{y}] = -1$  then
                if  $u \leq w$  then  $\hat{w} := w$ 
                else  $\hat{w} := \bigwedge^{\leq} \{u, w\}$ 
                 $\mathbf{points}[\hat{w}].\text{add}(\mathbf{y})$ 
                 $\mathbf{status}[\mathbf{y}] := 0$ 
                 $\mathbf{progress}[\hat{w}] := \text{true}$ 
                while  $u < \hat{w}$  do  $\hat{w} := \text{Flood}(\hat{w})$ 
if  $u = v_{\min}$  then
     $w := \varepsilon$ 
else
     $w := \bigvee^{\leq} \{w' \in \mathbb{V} \mid w' < u\}$ 
    while  $\mathbf{progress}[w] = \text{false}$  do  $w := \bigvee^{\leq} \{w' \in \mathbb{V} \mid w' < w\}$ 
     $\text{create\_edge}(\mathbf{nodes}[u][\mathbf{index}[u]], \mathbf{nodes}[w][\mathbf{index}[w]])$  // new edge in  $\triangleleft$ 
progress[ $u$ ] = false
index[ $u$ ]++
    
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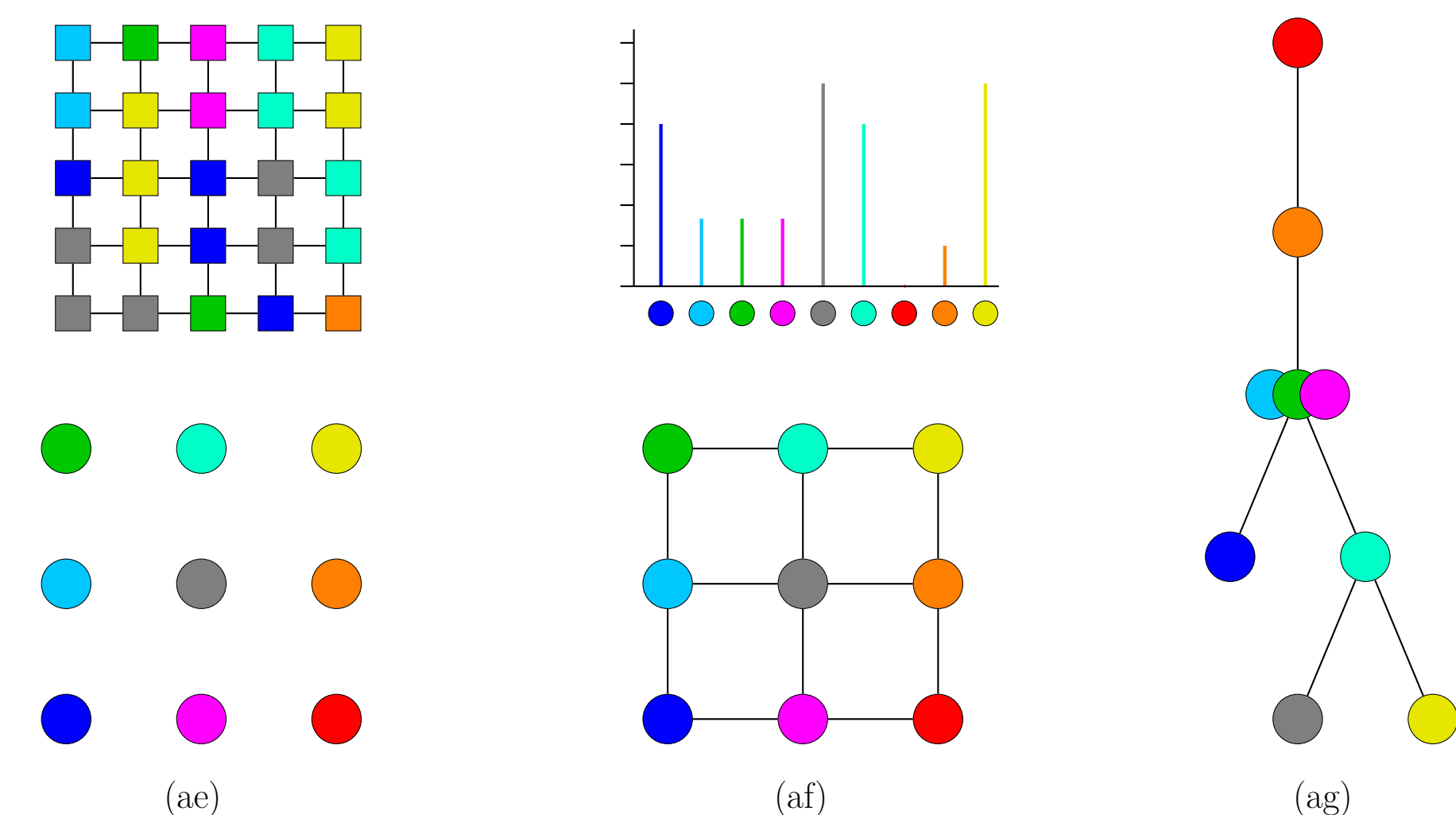
## Hierarchical order construction (1/2): (Pre)ordering the value set

Building the MCT requires a hierarchical order on  $\mathbb{V}$ .

First, we can build a hierarchical preorder  $\leq_{\mathbb{V}}$  on  $\mathbb{V}$ . This can be done by building the CT of an “image” composed by the value set. It is only required that  $\mathbb{V}$  be endowed with:

- an adjacency  $\sim_{\mathbb{V}}$ , allowing to map a graph structure on  $\mathbb{V}$ ;
- a function  $\delta_{\mathbb{V}} : \mathbb{V} \rightarrow \mathbb{N}$ , allowing to associate to each element of  $\mathbb{V}$  a value within the totally ordered set  $(\mathbb{N}, \leq)$ .

The CT of  $\delta_{\mathbb{V}}$  is a hierarchical preorder  $\leq_{\mathbb{V}}$  on  $\mathbb{V}$ .

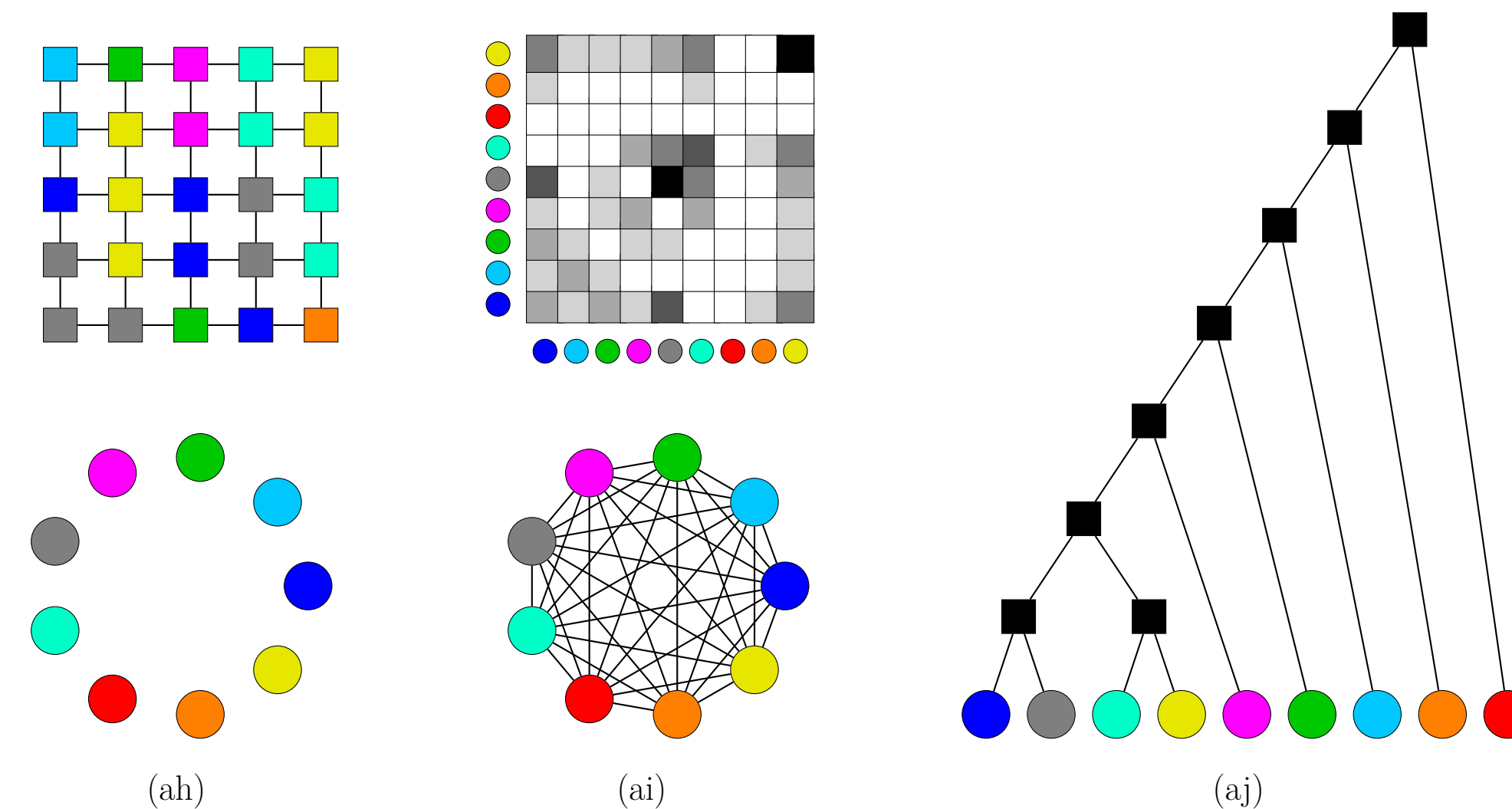


## Hierarchical order construction (2/2): Ordering the enriched value set

Second, we can build hierarchical order  $\leq_{\mathbb{W}}$  on  $\mathbb{W} \supset \mathbb{V}$  so that the elements of  $\mathbb{V}$  are the maximal elements with respect to  $\leq_{\mathbb{W}}$ .

This can be done by building the binary partition tree (BPT) [2] of an “image” composed by the value set  $\leq_{\mathbb{V}}$ . It is only required that  $\mathbb{V}$  be endowed with:

- an adjacency  $\sim_{\mathbb{V}}$ , allowing to map a graph structure on  $\mathbb{V}$ ;
- a priority function  $\delta_{\sim_{\mathbb{V}}} : \sim_{\mathbb{V}} \rightarrow \mathbb{N}$ , allowing to determine the couples of nodes to be merged in priority.



## References

- [1] C. Kurtz, B. Naegel, and N. Passat. Connected filtering based on multivalued component-trees. IEEE Transactions on Image Processing, 23:5152–5164, 2014.
- [2] P. Salembier and L. Garrido. Binary partition tree as an efficient representation for image processing, segmentation, and information retrieval. IEEE Transactions on Image Processing, 9:561–576, 2000.
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## Funding

This work was supported by the French Agence Nationale de la Recherche (grants ANR-20-THIA-0006, ANR-20-CE45-0011, ANR-22-CE45-0034 and ANR-23-CE45-0015).